

**ADVANCED GCE  
MATHEMATICS**

Mechanics 4

**4731**

Candidates answer on the answer booklet.

**OCR supplied materials:**

- 8 page answer booklet (sent with general stationery)
- List of Formulae (MF1)

**Other materials required:**

- Scientific or graphical calculator

**Thursday 23 June 2011  
Morning**

**Duration:** 1 hour 30 minutes



**INSTRUCTIONS TO CANDIDATES**

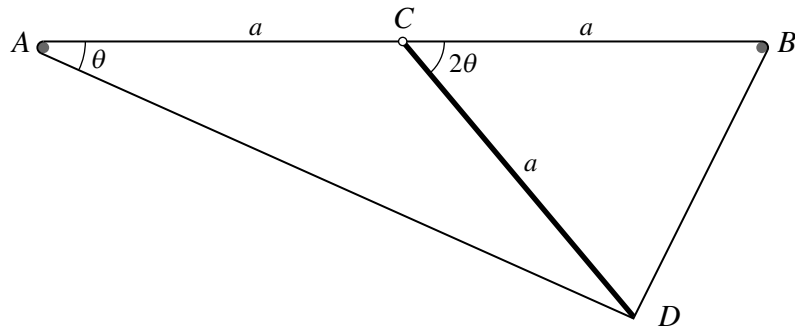
- Write your name, centre number and candidate number in the spaces provided on the answer booklet. Please write clearly and in capital letters.
- Use black ink. Pencil may be used for graphs and diagrams only.
- Read each question carefully. Make sure you know what you have to do before starting your answer.
- Answer **all** the questions.
- Do **not** write in the bar codes.
- Give non-exact numerical answers correct to 3 significant figures unless a different degree of accuracy is specified in the question or is clearly appropriate.
- The acceleration due to gravity is denoted by  $g \text{ m s}^{-2}$ . Unless otherwise instructed, when a numerical value is needed, use  $g = 9.8$ .
- You are permitted to use a scientific or graphical calculator in this paper.

**INFORMATION FOR CANDIDATES**

- The number of marks is given in brackets [ ] at the end of each question or part question.
- **You are reminded of the need for clear presentation in your answers.**
- The total number of marks for this paper is **72**.
- This document consists of **4** pages. Any blank pages are indicated.

- 1 When the power is turned off, a fan disk inside a jet engine slows down with constant angular deceleration  $0.8 \text{ rad s}^{-2}$ .
- (i) Find the time taken for the angular speed to decrease from  $950 \text{ rad s}^{-1}$  to  $750 \text{ rad s}^{-1}$ . [2]
- (ii) Find the angle through which the disk turns as the angular speed decreases from  $220 \text{ rad s}^{-1}$  to  $200 \text{ rad s}^{-1}$ . [2]
- (iii) Find the time taken for the disk to make the final 10 revolutions before coming to rest. [3]
- 2 A straight rod  $AB$  has length  $a$ . The rod has variable density, and at a distance  $x$  from  $A$  its mass per unit length is  $ke^{-\frac{x}{a}}$ , where  $k$  is a constant. Find, in an exact form, the distance of the centre of mass of the rod from  $A$ . [7]
- 3 A uniform rod  $XY$ , of mass  $5 \text{ kg}$  and length  $1.8 \text{ m}$ , is free to rotate in a vertical plane about a fixed horizontal axis through  $X$ . The rod is at rest with  $Y$  vertically below  $X$  when a couple of constant moment is applied to the rod. It then rotates, and comes instantaneously to rest when  $XY$  is horizontal.
- (i) Find the moment of the couple. [4]
- (ii) Find the angular acceleration of the rod
- (a) immediately after the couple is first applied, [3]
- (b) when  $XY$  is horizontal. [2]

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Two small smooth pegs  $A$  and  $B$  are fixed at a distance  $2a$  apart on the same horizontal level, and  $C$  is the mid-point of  $AB$ . A uniform rod  $CD$ , of mass  $m$  and length  $a$ , is freely pivoted at  $C$  and can rotate in the vertical plane containing  $AB$ , with  $D$  below the level of  $AB$ . A light elastic string, of natural length  $a$  and modulus of elasticity  $3mg$ , passes round the peg  $A$  and its ends are attached to  $C$  and  $D$ . Another light elastic string, of natural length  $a$  and modulus of elasticity  $4mg$ , passes round the peg  $B$  and its ends are also attached to  $C$  and  $D$ . The angle  $CAD$  is  $\theta$ , where  $0 < \theta < \frac{1}{2}\pi$ , so that the angle  $BCD$  is  $2\theta$  (see diagram).

- (i) Taking  $AB$  as the reference level for gravitational potential energy, show that the total potential energy of the system is

$$\frac{1}{2}mga(14 - 2 \cos 2\theta - \sin 2\theta). \quad [5]$$

- (ii) Find the value of  $\theta$  for which the system is in equilibrium. [3]

- (iii) Determine whether this position of equilibrium is stable or unstable. [2]

- 5 The region inside the circle  $x^2 + y^2 = a^2$  is rotated about the  $x$ -axis to form a uniform solid sphere of radius  $a$  and volume  $\frac{4}{3}\pi a^3$ . The mass of the sphere is  $10M$ .

(i) Show by integration that the moment of inertia of the sphere about the  $x$ -axis is  $4Ma^2$ . (You may assume the standard formula  $\frac{1}{2}mr^2$  for the moment of inertia of a uniform disc about its axis.) [6]

The sphere is free to rotate about a fixed horizontal axis which is a diameter of the sphere. A particle of mass  $M$  is attached to the lowest point of the sphere. The sphere with the particle attached then makes small oscillations as a compound pendulum.

(ii) Find, in terms of  $a$  and  $g$ , the approximate period of these oscillations. [5]

- 6 Two ships  $P$  and  $Q$  are moving on straight courses with constant speeds. At one instant  $Q$  is 80 km from  $P$  on a bearing of  $220^\circ$ . Three hours later,  $Q$  is 36 km due south of  $P$ .

(i) Show that the velocity of  $Q$  relative to  $P$  is  $19.1 \text{ km h}^{-1}$  in the direction with bearing  $063.8^\circ$  (both correct to 3 significant figures). [5]

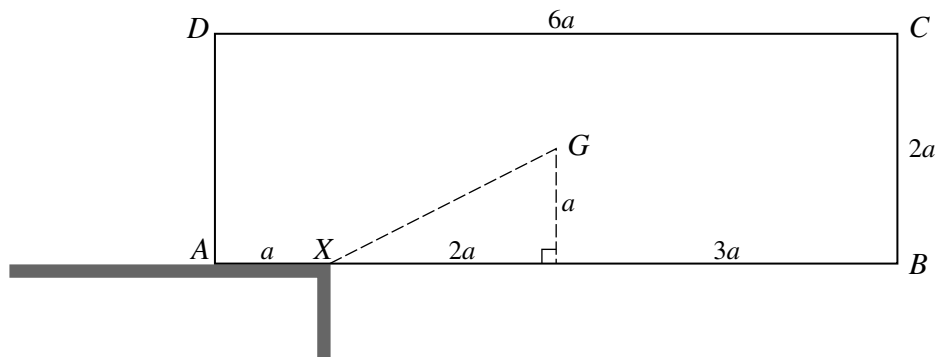
(ii) Find the shortest distance between the two ships in the subsequent motion. [2]

Given that the speed of  $P$  is  $28 \text{ km h}^{-1}$  and  $Q$  is travelling in the direction with bearing  $105^\circ$ , find

(iii) the bearing of the direction in which  $P$  is travelling, [3]

(iv) the speed of  $Q$ . [2]

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A uniform rectangular block of mass  $m$  and cross-section  $ABCD$  has  $AB = CD = 6a$  and  $AD = BC = 2a$ . The point  $X$  is on  $AB$  such that  $AX = a$  and  $G$  is the centre of  $ABCD$ . The block is placed with  $AB$  perpendicular to the straight edge of a rough horizontal table.  $AX$  is in contact with the table and  $XB$  overhangs the edge (see diagram). The block is released from rest in this position, and it rotates without slipping about a horizontal axis through  $X$ .

(i) Find the moment of inertia of the block about the axis of rotation. [3]

For the instant when  $XG$  is horizontal,

(ii) show that the angular acceleration of the block is  $\frac{3\sqrt{5}g}{25a}$ , [2]

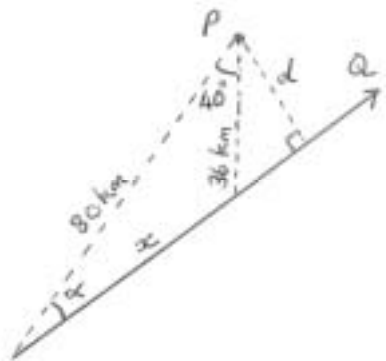
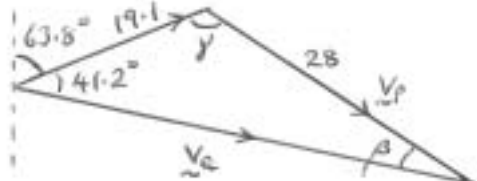
(iii) find the angular speed of the block, [3]

(iv) show that the force exerted by the table on the block has magnitude  $\frac{2\sqrt{70}}{25}mg$ . [8]

1 (i)	Using $\omega_2 = \omega_1 + \alpha t$ , $750 = 950 - 0.8t$ Time taken is 250 s	M1 A1 [2]	
(ii)	Using $\omega_2^2 = \omega_1^2 + 2\alpha\theta$ , $200^2 = 220^2 - 1.6\theta$ Angle is 5250 rad	M1 A1 [2]	
(iii)	Angle is $20\pi$ rad Using $\theta = \omega_2 t - \frac{1}{2}\alpha t^2$ , $20\pi = 0 + 0.4t^2$  Time taken is 12.5 s (3 sf)	B1 M1  A1 [3]	or equivalent; e.g. finding $\omega_1 = 10.03$ and then $t = \omega_1 \div 0.8$ <i>Accept <math>\sqrt{50\pi}</math> or <math>5\sqrt{2\pi}</math></i>
2	$m = \int_0^a k e^{-\frac{x}{a}} dx$ $= k \left[ -a e^{-\frac{x}{a}} \right]_0^a \quad (= ka(1 - e^{-1}))$ $m\bar{x} = \int_0^a x k e^{-\frac{x}{a}} dx$ $= k \left[ -ax e^{-\frac{x}{a}} - a^2 e^{-\frac{x}{a}} \right]_0^a$ $= ka^2(1 - 2e^{-1})$ $\bar{x} = \frac{ka^2(1 - 2e^{-1})}{ka(1 - e^{-1})}$ $= \frac{a(1 - 2e^{-1})}{1 - e^{-1}} = \frac{a(e - 2)}{e - 1}$	M1 A1  M1 M1 A1 A1  A1 [7]	For $\int e^{-\frac{x}{a}} dx$ For $-a e^{-\frac{x}{a}}$  For $\int x e^{-\frac{x}{a}} dx$ Integration by parts For $-ax e^{-\frac{x}{a}} - a^2 e^{-\frac{x}{a}}$  For $a^2(1 - 2e^{-1})$ or exact equivalent
3 (i)	WD by couple is $C \times \frac{\pi}{2}$ Change in PE is $5 \times 9.8 \times 0.9$ By conservation of energy, $C \times \frac{\pi}{2} = 5 \times 9.8 \times 0.9$ Moment of couple is 28.1 Nm (3 sf)	B1 B1  M1 A1 [4]	Must clearly be PE (not moment)  Equation involving WD and PE
(ii) (a)	$I = \frac{4}{3} \times 5 \times 0.9^2 \quad (= 5.4)$ $28.075 = 5.4\alpha$ Angular acceleration is $5.20 \text{ rad s}^{-2}$ (3 sf)	B1 M1 A1 ft [3]	<i>Can be earned anywhere in the question</i> Applying $C = I\alpha$ ft is $C \div I$
(ii) (b)	$28.075 - 5 \times 9.8 \times 0.9 = 5.4\alpha$ Angular acceleration is $(-) 2.97 \text{ rad s}^{-2}$ (3 sf)	M1  A1 [2]	Rotational equation of motion (3 terms) <i>(Allow 1.8 instead of 0.9 etc)</i>

<p><b>4</b> <b>(i)</b></p>	<p>GPE is <math>-mg(\frac{1}{2}a \sin 2\theta)</math>  EPE is <math>\frac{3mg}{2a} AD^2 + \frac{4mg}{2a} BD^2</math>  <math>= \frac{3mg}{2a} (2a \cos \theta)^2 + \frac{4mg}{2a} (2a \sin \theta)^2</math>  <math>= mga(6 \cos^2 \theta + 8 \sin^2 \theta)</math>  <math>= mga(3 + 3 \cos 2\theta + 4 - 4 \cos 2\theta)</math>  <math>= mga(7 - \cos 2\theta)</math>  Total PE is <math>V = mga(7 - \cos 2\theta) - \frac{1}{2}mga \sin 2\theta</math>  <math>= \frac{1}{2}mga(14 - 2 \cos 2\theta - \sin 2\theta)</math></p>	<p>B1 M1 A1 M1 A1 ag <b>[5]</b></p>	<p><i>Negative sign is essential, but may be implied later</i>  Any correct form  Expressing EPE in terms of <math>\cos 2\theta</math></p>
<p><b>(ii)</b></p>	<p><math>\frac{dV}{d\theta} = \frac{1}{2}mga(4 \sin 2\theta - 2 \cos 2\theta)</math>  <math>\frac{dV}{d\theta} = 0</math> when <math>4 \sin 2\theta = 2 \cos 2\theta</math>  <math>\tan 2\theta = 0.5</math>  <math>\theta = 0.232</math> (3 sf)</p>	<p>B1 M1 A1 <b>[3]</b></p>	<p>Equating to zero and solving  Accept <math>13.3^\circ</math></p>
<p><b>(iii)</b></p>	<p><math>\frac{d^2V}{d\theta^2} = \frac{1}{2}mga(8 \cos 2\theta + 4 \sin 2\theta)</math>  When <math>\theta = 0.232</math>, <math>\frac{d^2V}{d\theta^2} &gt; 0</math>  So the equilibrium is stable</p>	<p>M1 A1 <b>[2]</b></p>	<p>Fully correct working only</p>

<p>5 (i)</p>	$\left(\frac{4}{3}\pi a^3\right)\rho = 10M, \text{ so } \rho = \frac{15M}{2\pi a^3}$ $I = \sum \frac{1}{2}(\rho\pi y^2 \delta x)y^2 = \frac{1}{2}\rho\pi \int y^4 dx$ $= \frac{1}{2}\rho\pi \int_{-a}^a (a^2 - x^2)^2 dx$ $= \frac{1}{2}\rho\pi \left[ a^4x - \frac{2}{3}a^2x^3 + \frac{1}{5}x^5 \right]_{-a}^a$ $= \frac{1}{2}\rho\pi \left( a^5 - \frac{2}{3}a^5 + \frac{1}{5}a^5 \right) \times 2$ $= \frac{8}{15}\rho\pi a^5$ $= \frac{8}{15} \times \frac{15M}{2\pi a^3} \times \pi a^5 = 4Ma^2$	<p>M1 M1 A1 A1 A1 A1 ag [6]</p>	<p>For <math>\int y^4 dx</math> Correct integral expression including limits For <math>a^4x - \frac{2}{3}a^2x^3 + \frac{1}{5}x^5</math></p>
<p>(ii)</p>	$MI \text{ is } 4Ma^2 + Ma^2 = 5Ma^2$ <hr/> $-Mga \sin \theta = 5Ma^2 \ddot{\theta}$ $\ddot{\theta} \approx -\frac{g}{5a} \theta$ <p>Period is <math>2\pi \sqrt{\frac{5a}{g}}</math></p>	<p>M1 A1 M1 A1 [5]</p>	<p>Equation of motion Obtaining period</p>
	<p><i>Alternative for last 3 marks of (ii)</i></p> $11M \bar{x} = 10M(0) + Ma$ $\bar{x} = \frac{1}{11}a$ $\text{Period is } 2\pi \sqrt{\frac{I}{mgh}} = 2\pi \sqrt{\frac{5Ma^2}{11Mg \frac{1}{11}a}}$ $= 2\pi \sqrt{\frac{5a}{g}}$	<p>M1 M1 A1</p>	<p>Finding centre of mass Using formula <i>Dependent on previous M1</i> Note <math>2\pi \sqrt{\frac{I}{Mgh}} = 2\pi \sqrt{\frac{5Ma^2}{Mga}}</math> is M0</p>

<p>6 (i)</p>	<p>As viewed from P</p>  $x^2 = 80^2 + 36^2 - 2 \times 80 \times 36 \cos 40^\circ$ $x = 57.30$ <p>Relative velocity has magnitude <math>\frac{x}{3} = 19.1 \text{ km h}^{-1}</math></p> $\frac{\sin \alpha}{36} = \frac{\sin 40^\circ}{57.30}$ $\alpha = 23.82^\circ$ <p>Relative velocity has bearing <math>40 + \alpha = 063.8^\circ</math></p>	<p>M1  M1 A1 ag M1 A1 ag [5]</p>	<p>Suitable diagram showing relative velocity <i>May be implied</i></p> <p>Or other valid method for finding a relevant angle</p>
	<p>OR, using components, Diagram M1 East <math>\frac{80 \sin 40^\circ}{3}</math> (= 17.14) M1 North <math>\frac{80 \cos 40^\circ - 36}{3}</math> (= 8.428) M1 Speed <math>\sqrt{17.14^2 + 8.428^2} = 19.1</math> A1 ag Bearing <math>\tan^{-1} \frac{17.14}{8.428} = 063.8^\circ</math> A1 ag</p>		<p>Implied by both components correct</p>
<p>(ii)</p>	<p>Shortest distance <math>d = 80 \sin 23.82^\circ</math> <math>= 32.3 \text{ km}</math> (3 sf)</p>	<p>M1 A1 [2]</p>	<p>or <math>36 \sin 63.8^\circ</math></p>
<p>(iii)</p>	 $\frac{\sin \beta}{19.10} = \frac{\sin 41.18^\circ}{28}$ $\beta = 26.69^\circ$ <p>Bearing of P is <math>105 + \beta = 131.7^\circ</math> (1 dp)</p>	<p>M1  M1 A1 [3]</p>	<p>Velocity diagram <i>May be implied</i> (28 opposite a known angle between sides with positive and negative slopes)</p> <p><i>Using components for (iii) and (iv)</i> <i>M2A1 for <math>\theta = 131.7^\circ</math> or <math>v = 39.4</math></i> <i>M1A1 for other quantity</i></p>
<p>(iv)</p>	$\frac{v_Q}{\sin 112.13^\circ} = \frac{28}{\sin 41.18^\circ}$ <p>Speed of Q is <math>39.4 \text{ km h}^{-1}</math> (3 sf)</p>	<p>M1 A1 [2]</p>	<p>Or other valid method for finding speed</p>

7 (i)	$XG = \sqrt{5}a$ $I = \frac{1}{3}m\{a^2 + (3a)^2\} + m(\sqrt{5}a)^2$ $= \frac{25}{3}ma^2$	B1 M1 A1 [3]	For $I_G = \frac{1}{3}m\{a^2 + (3a)^2\}$ Using parallel axes rule
	OR, other complete method, e.g. $\frac{4}{3}\left(\frac{1}{6}m\right)\left(\left(\frac{1}{2}a\right)^2 + a^2\right) + \frac{4}{3}\left(\frac{5}{6}m\right)\left(\left(\frac{5}{2}a\right)^2 + a^2\right)$ $I = \frac{25}{3}ma^2$	M1 A1 A1	Correct expression for $I$
(ii)	$mg(\sqrt{5}a) = I\alpha$ $\sqrt{5}mga = \frac{25}{3}ma^2\alpha$ $\alpha = \frac{3\sqrt{5}g}{25a}$	M1  A1 ag [2]	Allow, e.g. $mg(2a) = I\alpha$
(iii)	$\frac{1}{2}I\omega^2 = mga$ $\frac{25}{6}ma^2\omega^2 = mga$ $\omega = \sqrt{\frac{6g}{25a}}$	M1 A1 ft A1 [3]	Equation involving KE and PE
(iv)	$H = m(XG)\omega^2$ $= m(\sqrt{5}a)\left(\frac{6g}{25a}\right)$ $= \frac{6\sqrt{5}}{25}mg$ $mg - V = m(XG)\alpha$ $V = mg - m(\sqrt{5}a)\left(\frac{3\sqrt{5}g}{25a}\right)$ $= \frac{2}{5}mg$ Force has magnitude $\sqrt{H^2 + V^2}$ $= \frac{2}{25}mg\sqrt{(3\sqrt{5})^2 + 5^2}$ $= \frac{2\sqrt{70}}{25}mg$	M1 A1  A1 ft  M1 A1  A1  M1 A1 ag [8]	For using acceleration $r\omega^2$ Or ( $F$ parallel to $BA$ , $\theta$ is angle $GXB$ ) $F - mg \sin \theta = m((AG)\omega^2 \cos \theta - (AG)\alpha \sin \theta)$ ft from incorrect $\omega$ only Or $F = \frac{mg(2\sqrt{5} + 12)}{25}$ For using acceleration $r\alpha$ Or ( $R$ parallel to $AD$ ) $mg \cos \theta - R = m((AG)\omega^2 \sin \theta + (AG)\alpha \cos \theta)$ Or $R = \frac{mg(4\sqrt{5} - 6)}{25}$ Or $\sqrt{F^2 + R^2}$